









# **DynaLogger HF+/HF+s**

PN 101112 | NCM 9027.89.99 | HS 902789 (stainless steel base) PN 101110 | NCM 9027.89.99 | HS 902789 (aluminum base)

Datasheet Jul. 2024





#### **Overview**

The HF+/HF+s DynaLogger is designed to identify failure mode symptoms or defects in machinery and equipment in a wide variety of field applications. Due to its broad frequency spectrum, the HF+/HF+s delivers complete triaxial vibration and temperature monitoring for low to high-speed equipment. In addition, the solution features an online platform, which does not require local installation, with several tools that assist in data analysis and enable constant monitoring of asset health.

The HF+/HF+s DynaLogger has two monitoring modes: spectral/waveform and telemetry. Configurable telemetry monitoring in bands includes several metrics, such as acceleration, velocity, and RMS displacement, peak, peak-topeak, and crest factor, as well as skewness, kurtosis, and contact temperature. In spectral monitoring, different tools can be used: spectrum, waveform (linear, circular and orbital), frequency filters, cepstrum, spectral envelope (demodulation), autocorrelation, and multi-metrics.

## **Wireless Monitoring Solution**

- Tompact sensor with wide frequency range.
- ① Long battery life.
- Thigh resolution in frequency and amplitude.
- Over 40 telemetry metrics that can be applied in different frequency bands up to 13 kHz (under development).
- Dow-speed applications (less than 10 RPM).
- Sensor with low spectral noise.
- Truly simultaneous triaxial measurement.
- Remote sensor update.

### Main assets monitored

- Motors
- Pumps
- Fans
- Gearboxes
- Rollers and brakes
- Compressors and chillers
- Wind turbines
- Bearings in high and low-speed assets.



















Technical Specifications					
Model	HF+s (stainless steel base)				
	HF+ (aluminum base)				
Dimensions	39 x 39 x 35 mm				
Weight	97 g (stainless steel base)				
	73 g (aluminum base)				
Case Material	Lexan™				
Pin and base material	Stainless steel or Aluminum				
Color	Blue				
Mounting	Glued or Screwed				
Visual Signaling (LED)	Red / Green				
Accelerometer	MEMS triaxial				
Accelerometer Impact Limit	10,000 g em 0.2 ms				
Operating temperature <sup>1,2</sup>	-10°C ≤ T ≤ 84°C				
Certified operating temperature for use in explosive atmosphere	-10°C ≤ T ≤ 79°C				
Certif	ication				
	ANATEL/CE/ACMA/FCC/IC/INMETRO*				
Homologation / Certification	*For information about other certifications, please				
	refer to the last page				
Protection Degree	IP66/IP68/IP69				
Explosive Atmosphere	Ex ma IIB T6 Ga				
· ·	Ex ta IIIC T85 °C Da				
	tery				
Voltage	3 V				
Autonomy³	5 years				
Continuous Moni	toring (Telemetry)				
Sampling Period	1 to 60 min.				
	RMS Acceleration, Peak* and Peak-to-Peak*				
	RMS Velocity, Peak* and Peak-to-Peak*				
Monitored Metrics	RMS Displacement, Peak* and Peak-to-Peak*				
Worthtorea Wetries	Acceleration Skewness*				
*Under development	Acceleration Kurtosis*				
	Acceleration Crest factor (CF)*				
	Acceleration Crest factor + (CF+)*				
Taman anatoma manakatian	Contact Temperature				
Temperature resolution	0,01°C				
Frequency Bands (Factory standard)	34 Hz to 13 kHZ				
Frequency Bands (Under development)	3 Hz to 13 kHz (adjustable)				
Monitoring Profiles <sup>4</sup>	2 profiles				
Frequency Response (± 3 dB)	7.6 kHz				
Amplitude Range	Up to $\pm 16$ g				
Memory <sup>5</sup>	51,200 samples (adjustable)				

1 It is possible to monitor assets whose temperature exceeds 84°C, especially assets with intermittent characteristics and with room temperature below 24°C. However, Dynamox does not provide warranty in these cases. Specific condition for application outside explosive atmospheres. 2 The application at temperatures below 0°C impacts the battery autonomy. This effect worsens the lower the temperature, estimating a reduction of about 50% of useful life in applications at -20°C. Specific condition for application outside explosive atmospheres. 3 Estimated value for a standard monitoring condition with 1 or 2 daily spectral collections, telementry intervals of 5 to 30 minutes and operating temperature between 20°C and 60°C. 4 Monitoring profiles can be understood as set configurations of vibration metrics (in velocity, acceleration and displacement) in a given frequency band. 5 Each telemetry metric corresponds to the allocation of a sample in memory. In practice, the time to fill the memory depends on the sample interval and number of metrics configured. It is important to remember that when data is collected (via App or Gateway), the memory is emptied.



















Communication and System							
Bluetooth	BLE 5.3 / 2,400 – 2,483.5 MHz						
Free Field Range <sup>1</sup>	100 m						
RF Output Power	0.4 dBm						
App Communication	Android and iOS						
Spectral Monitoring and Waveform							
Analysis Tools	Spectrum						
	Frequency Filters						
	Envelope (demodulation)						
	Cepstrum						
	Spectral Waterfall						
Analysis 100is	Autocorrelation						
	Circular and orbital waveform						
	Advanced metrics: multiband RMS, peak-to-						
	peak, Kurtosis, CF, CF+, Carpet energy and						
	RMS Envelope.						
Frequency Response ( $\pm$ 5%)	7 kHz						
Frequency Response ( $\pm$ 3dB)	7.6 kHz						
Spectral noise density	< 75 μg/√Hz						
Sample Rate	Up to 26 kHz						
Minimum Frequency Resolution	0.006 Hz (8 bits) and 0.012 Hz (16 bits)						
Minimum Amplitude Resolution <sup>2</sup>	16 mg (8 bits) and 61 μg (16 bits)						
Amplitude Range	Up to <u>+</u> 16 g						
Lines of Resolution (LOR)	98,304 (uniaxial) and 32,768 (triaxial)						
Maximum Frequency	571 Hz to 13 kHz (adjustable)						
Maximum Collection Time <sup>3</sup>	172.2 s (uniaxial) and 57.3 s (triaxial)						

## **Spectral Monitoring Settings**

Simultaneous Triaxial									
Max. Freq. (Hz)	Duration (s)								
13,145	0.08	0.16	0.31	0.62	1.25	2.5	24.0		
6,572	0.16	0.31	0.62	1.25	2.5	5.0	12.0		
2,629	0.4	0.8	1.6	3.1	6.2	12.5	4.8		
1,314	0.8	1.6	3.1	6.2	12.5	24.9	2.4		
571	1.8	3.6	7.2	14.3	28.7	57.3	1.0		
No. Lines	1,024	2,048	4,096	8,192	16,384	32,768*	-		

Uniaxial									
Max. Freq. (Hz)	Duration (s)						Min. RPM <sup>4</sup>		
13,145	0.08	0.16	0.31	0.62	1.25	2.5	3.7	7.5	8.0
6,572	0.16	0.31	0.62	1.25	2.5	5.0	7.5	15.0	4.0
2,629	0.4	0.8	1.6	3.1	6.2	12.5	18.7	37.4	1.6
1,314	0.8	1.6	3.1	6.2	12.5	24.9	37.4	74.8	0.8
571	1.8	3.6	7.2	14.3	28.7	57.3	86.0	172.0	0.3
No. Lines	1,024	2,048	4,096	8,192	16,384	32,768	49,152	98,304*	-

<sup>1</sup> Reference in free field. Bluetooth communication distance may vary with obstacles, interference and device (cell phone or Gateway). 2 Calculated amplitude resolution is based on the accelerometer digital output in  $\mu$ g/LSB or mg/LSB. 3 Check the setting in the 'Spectral Monitoring Settings' table. 4 Minimum RPM based on the longest measurement time considering one full revolution of the shaft.













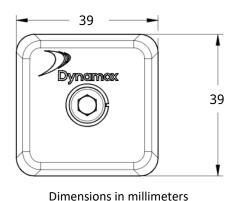


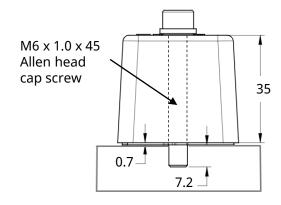






### **Geometric dimensions**





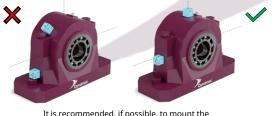


## **Quick Mounting Guide**

- Define the critical points of the machines to be monitored for the installation of the DynaLoggers.
- It is only necessary to install one DynaLogger per monitoring spot, as the devices are triaxial.
- Avoid installation in areas of the housings that present any stiffness loss. Example: cooling fins, covers, and protections. Try to install in rigid parts of the machine, preferably near the bearings.



- Align one of the axes of the DynaLogger with the actual axis of the machine. These axes are shown in the schematic above and on the body of the devices. A detailed installation guide can be found at Dynamox's <u>support website</u>.



It is recommended, if possible, to mount the DynaLoggers centrally on the component.





Mounting on cooling fins and covers is not recommended.

Note: For motors, it is recommended to mount a sensor on the drive end and another one on the non-drive end for complete monitoring.

Regarding the types of mounting, the HF+/HF+s DynaLogger can be:

**Screwed:** M6 screw with a length that allows a minimum 7.2 mm depth to the drilled surface. It is recommended to use a spring washer and to apply an 11 N-m torque.

**Glued:** After cleaning the mounting spot, apply adhesive glue to cover the entire sensor base. Dynamox recommends the adhesives DP8810, DP8710 and DP420 from 3M.



















#### **Certification/Countries**

INMETRO FCC CE ACMA IC MTC IFETEL SUBTEL ICASA WPC RSM\_SDoC CITC CE\_Turkey ASEP ZICTA AMRTP ARM INCM UKCA VoC EAC (stainless steel base) INMETRO FCC CE ACMA IC IFETEL ICASA WPC SDDPI EAC (aluminium base)

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